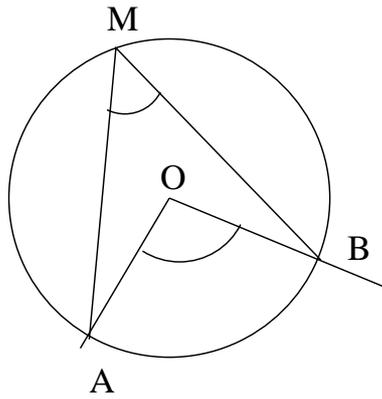
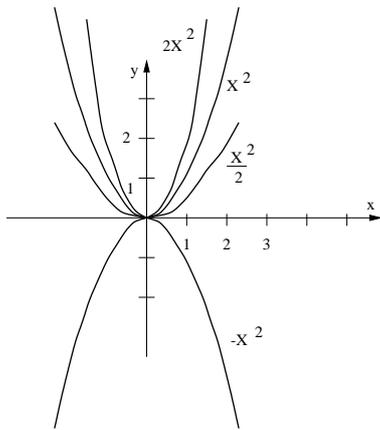


En gras le nom du fichier sans l'extension .eps

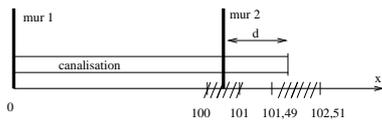
anglaucentre



ax2

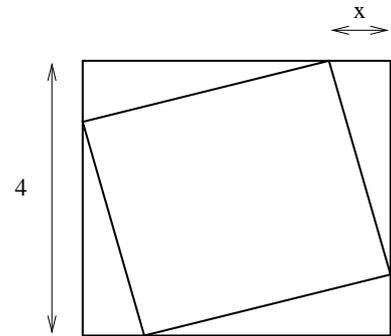


canalisation

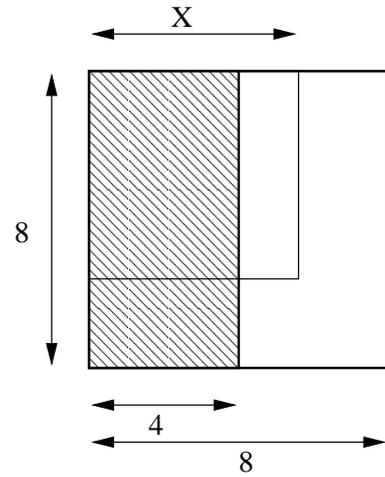


carres01

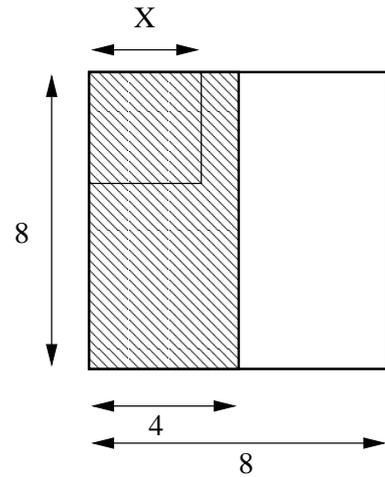
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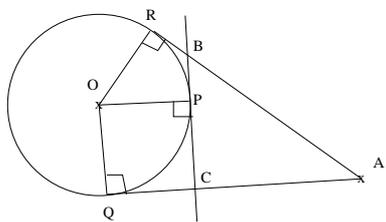


carres02

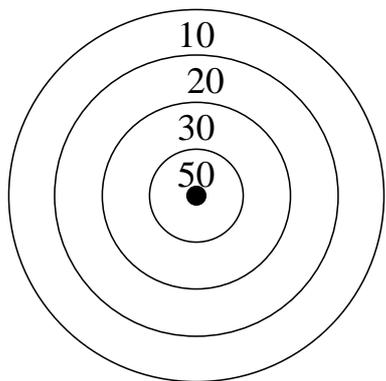


carres03

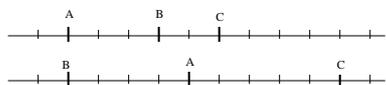




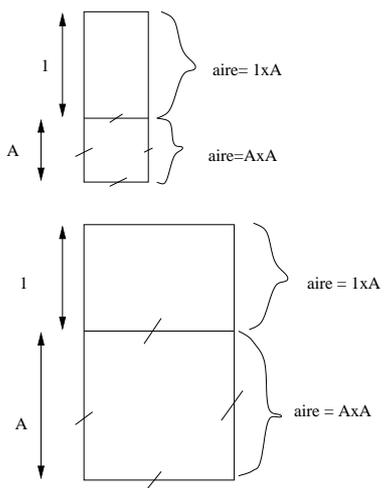
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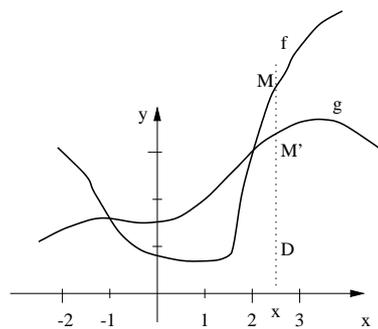
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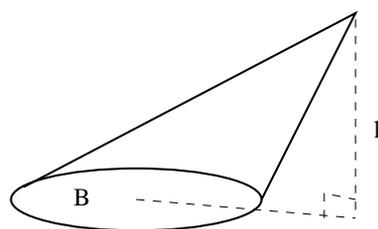
compar-a-a2



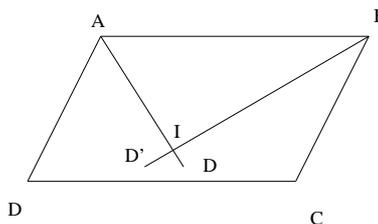
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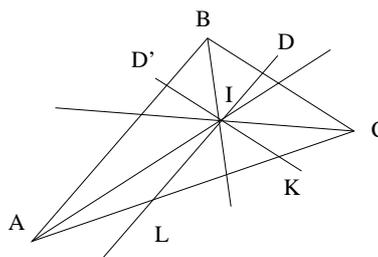
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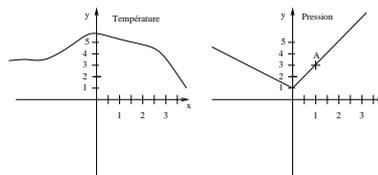
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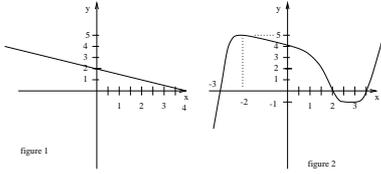
config-triangle



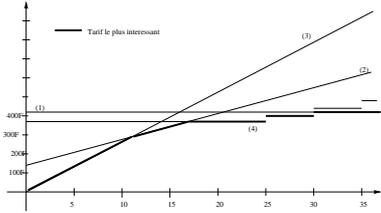
courbes01



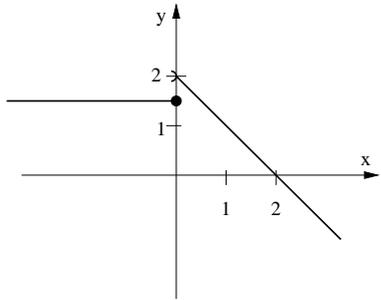
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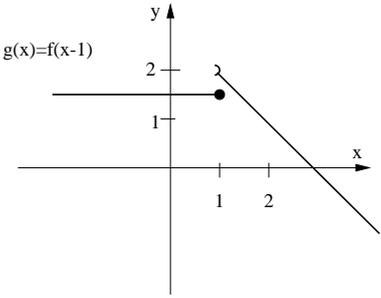
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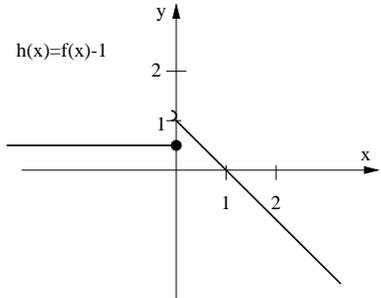
courbes04



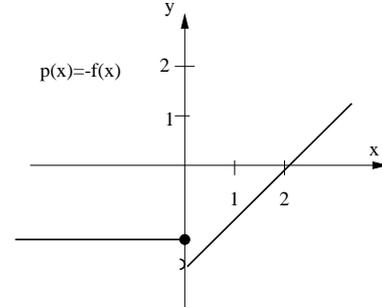
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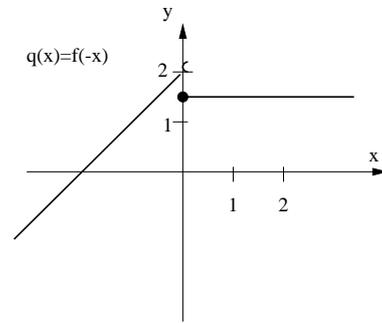
courbes06



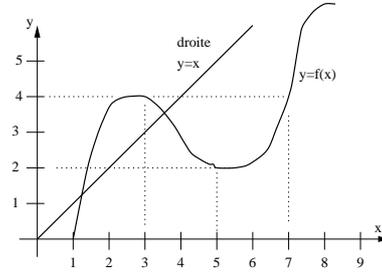
courbes07



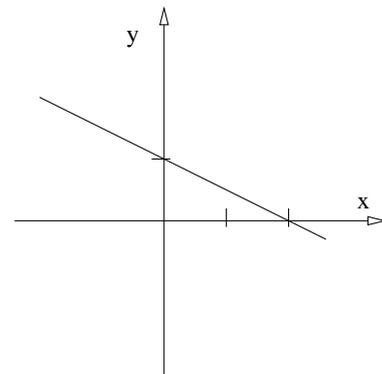
courbes08



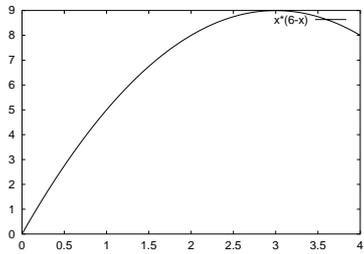
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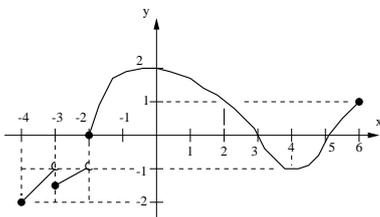
courbes10



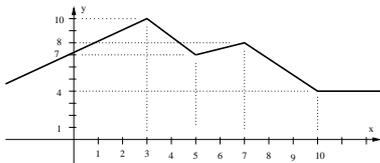
courbes11



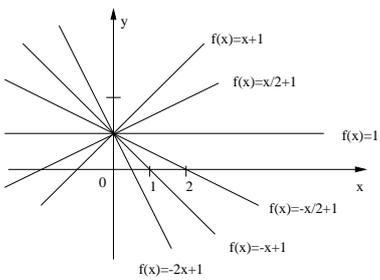
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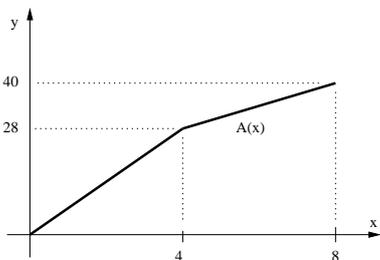
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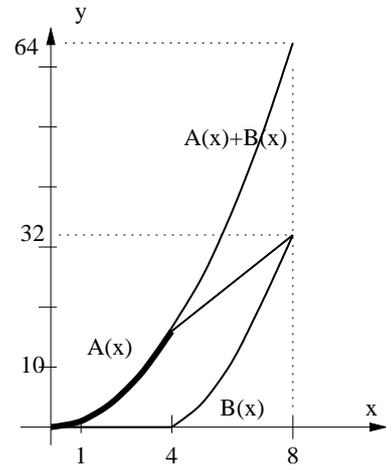
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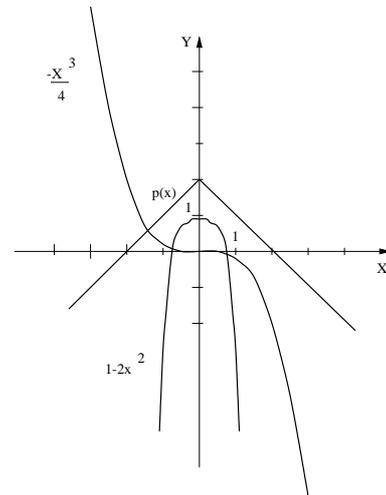
courbes15-aire



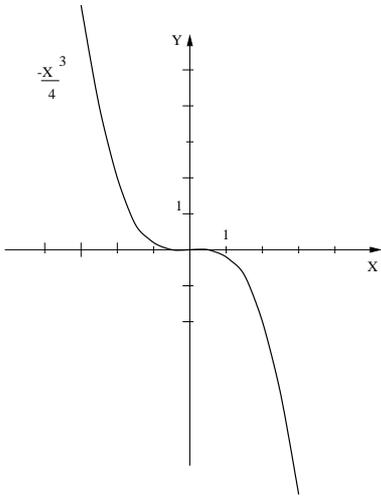
courbes16



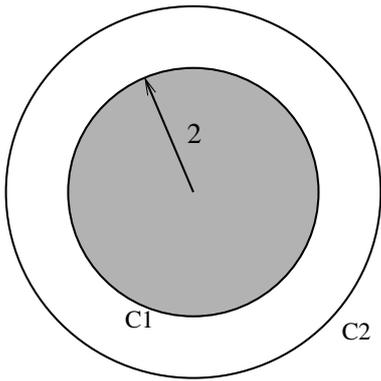
courbexcube-c



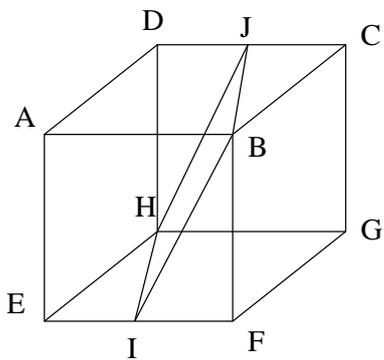
courbexcube



couronnel

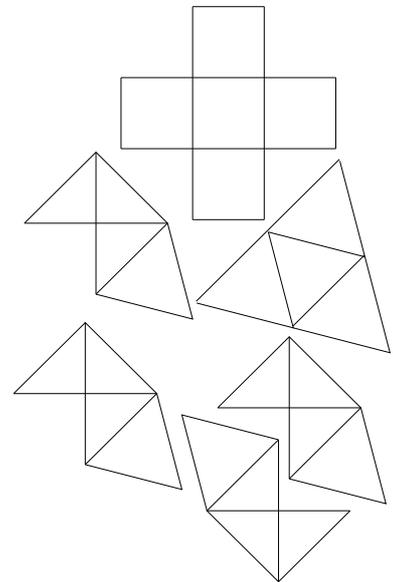
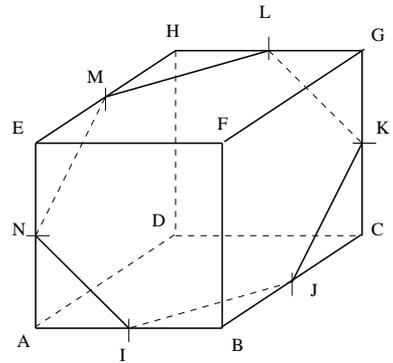


cube1



cube2

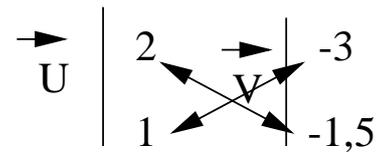
cube-tetraedre



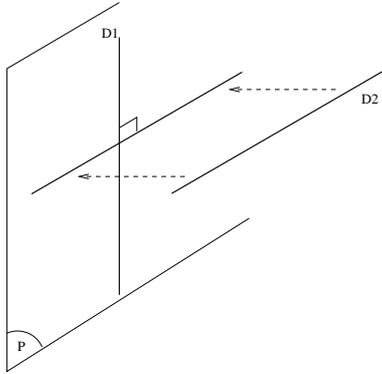
demonst-geom

Hypotheses	On veut obtenir....
A(xa;ya) B(xb;yb)	AB(xb-xa;yb-ya)
Traduction: → OA=xa i + ya j → OB=xb i + yb j	→ AB = (xb-xa) i + (yb-ya) j
Démonstration	

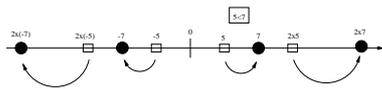
determinant



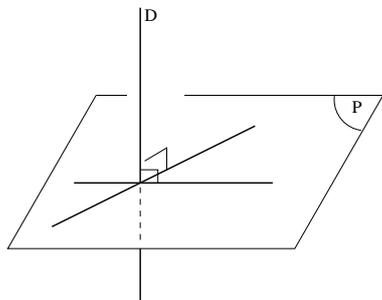
deux-droites



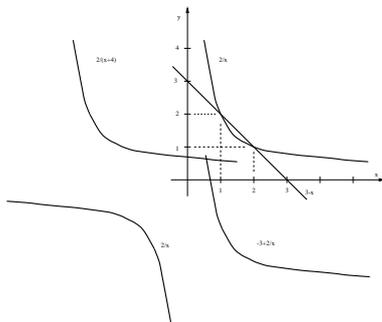
dilatation



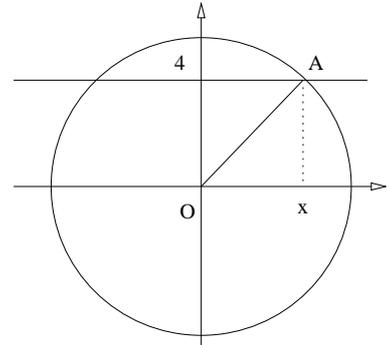
droite-plan



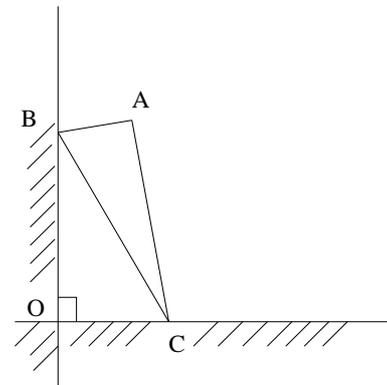
ds5c3



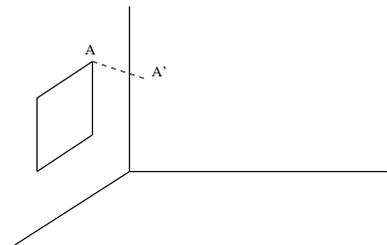
equations01



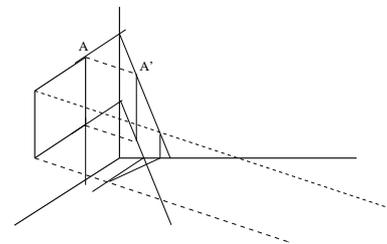
equerre



fenetre



fenetrec



fonct-m25

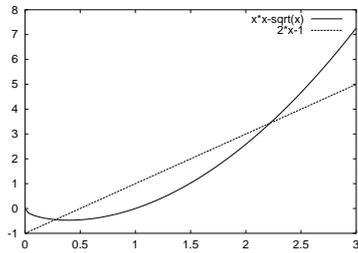


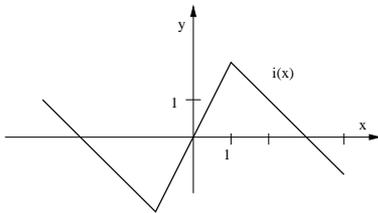
tableau-var-m25

x	0	0,4	∞
f(x)	0	-0,47	∞

fonct-impaire-t

x	-4	-1	0	1	4
i(x)	1	-2		2	-1

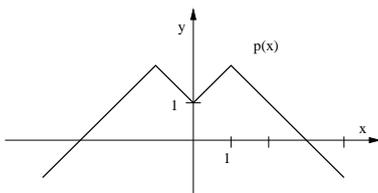
fonct-impaire



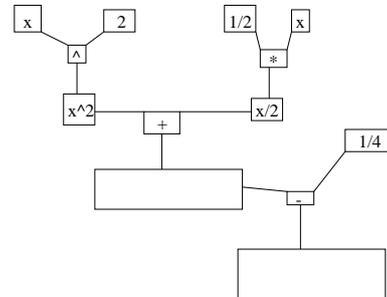
fonct-paire-t

x	-4	-1	0	1	4
p(x)	-1	2	1	2	-1

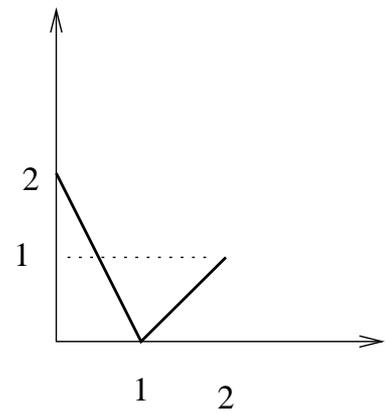
fonct-paire



fonction-arbre



fonction-test05



fonction01

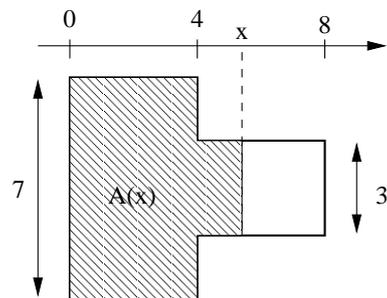
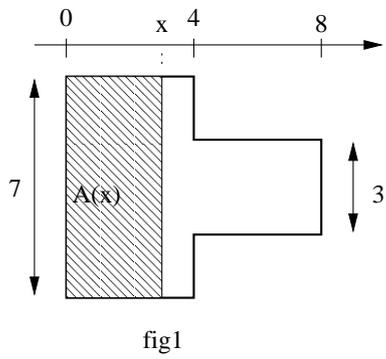
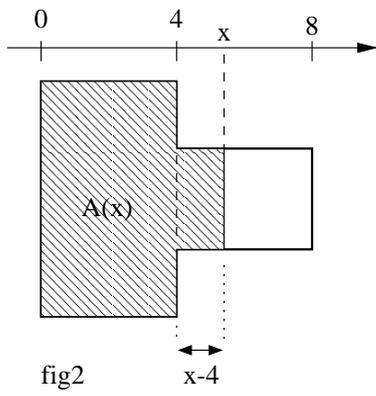


fig2

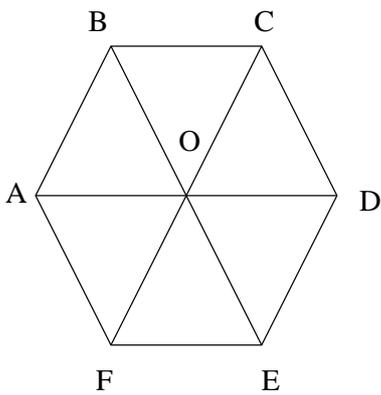
fonction02



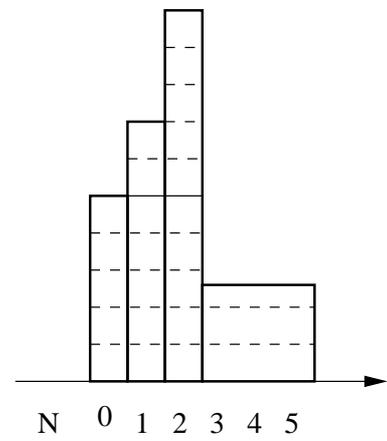
fonction03



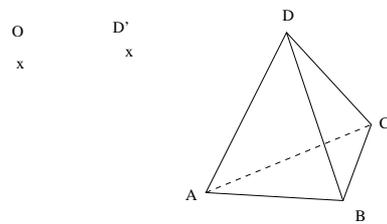
hexagone



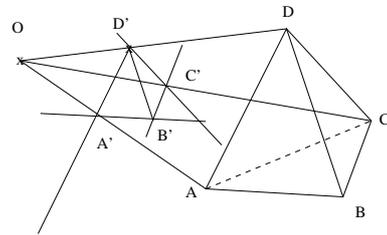
histo-m25



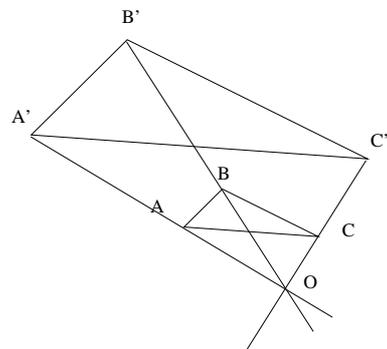
homoth3d1



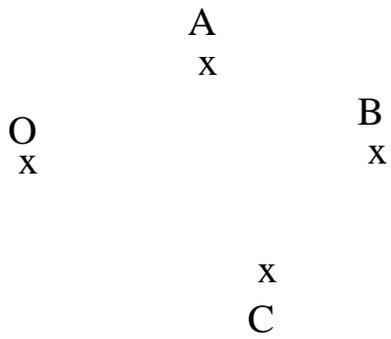
homoth3d1c



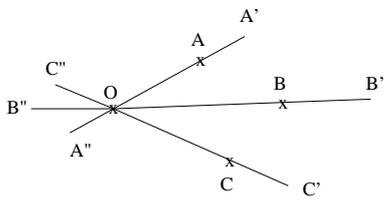
homothetie1



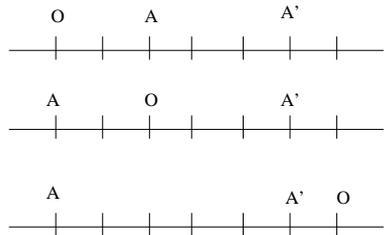
homothetie2



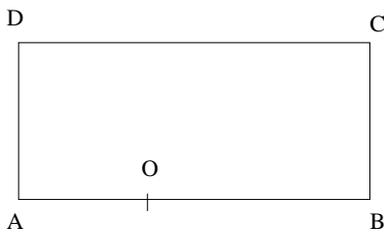
homothetic2c



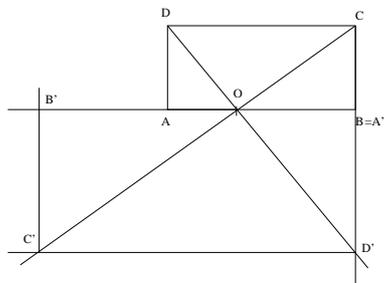
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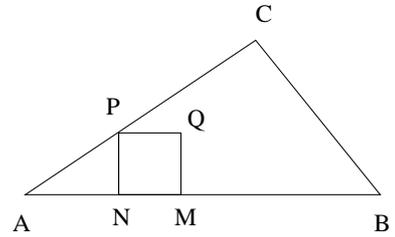
homothetic4



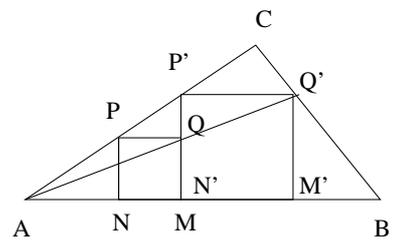
homothetic4c



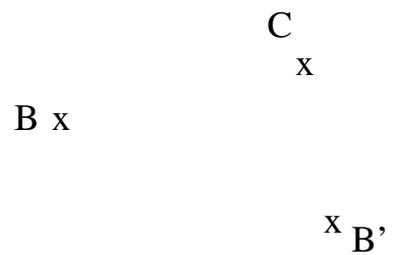
homothetic5



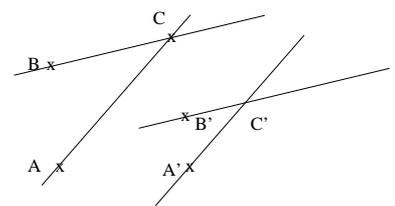
homothetic5c



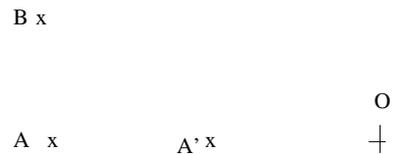
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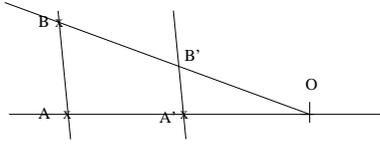
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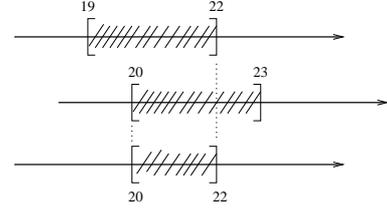
homothetic7



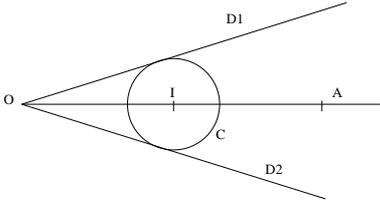
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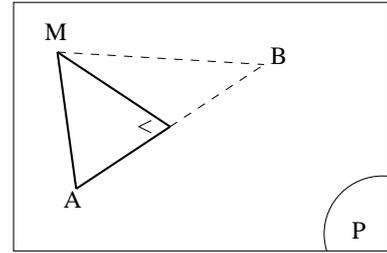
homothetie8



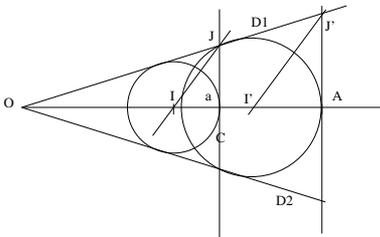
mediateur



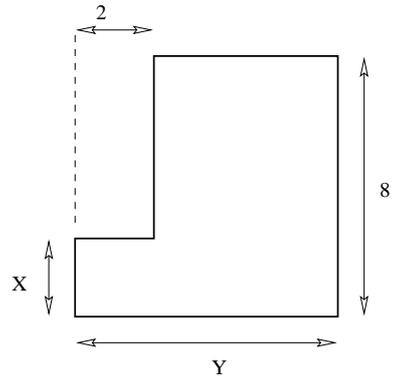
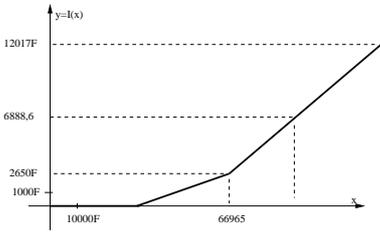
homothetie8c



mise-en-eq1



impots



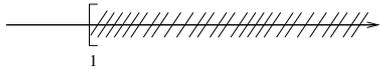
interv01



interv02

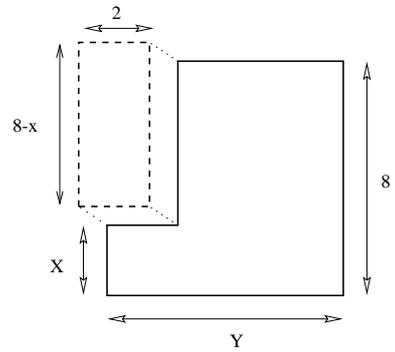


interv03

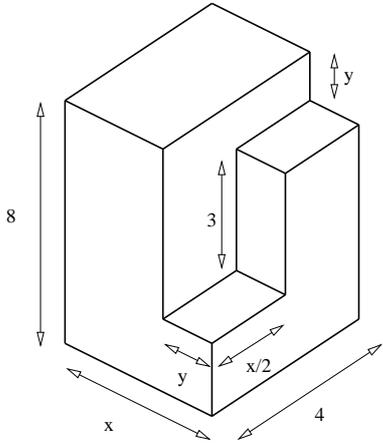


interv04

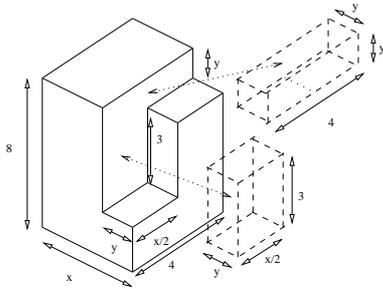
mise-en-eq1c



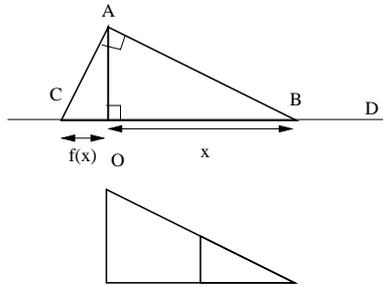
mise-en-eq2



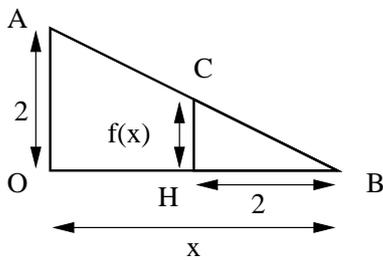
mise-en-eq2c



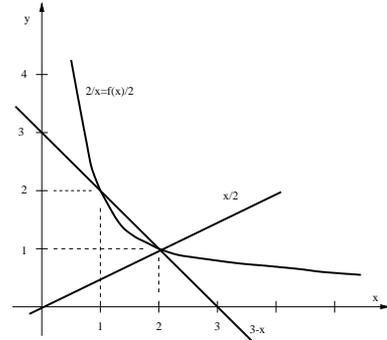
mise-en-eq3



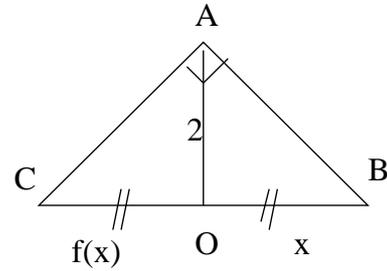
mise-en-eq3c



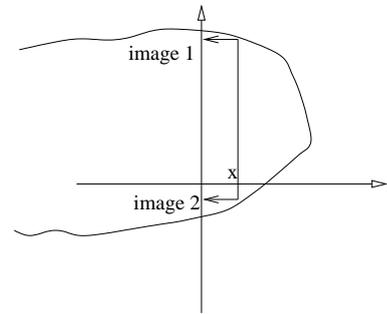
mise-en-eq3c2



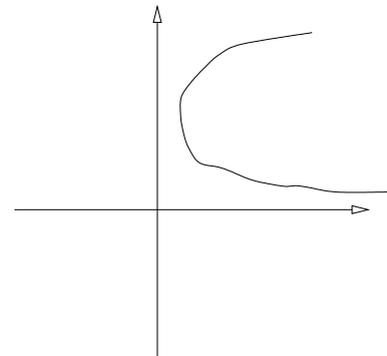
mise-en-eq3c3



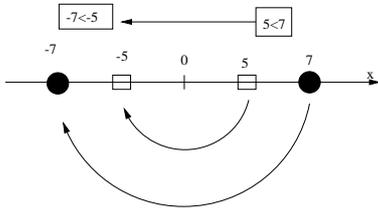
not-a-function



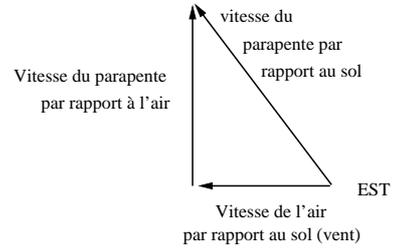
not-a-function2



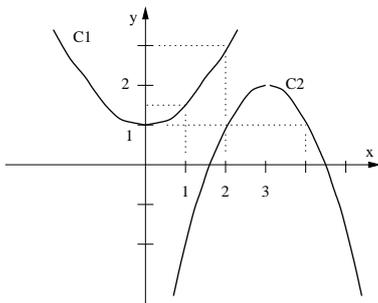
oppose



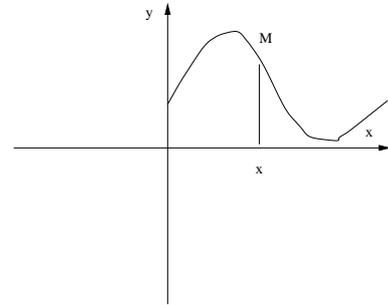
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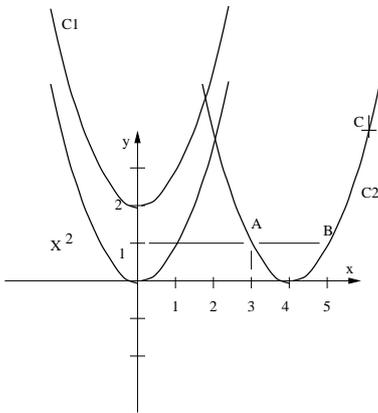
paraboles01



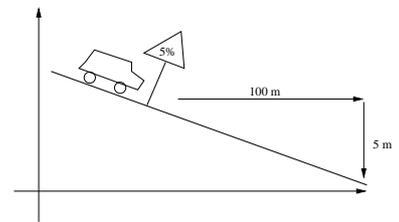
parite



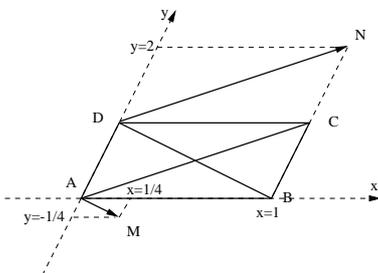
paraboles02



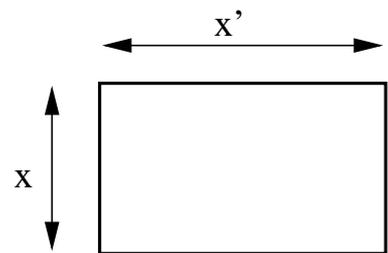
pente5pourcent



parallelogramme1

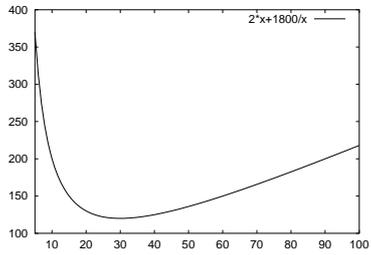


perimetre

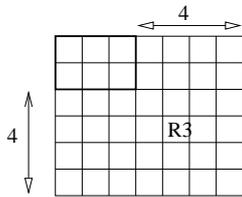
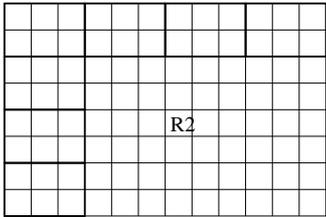
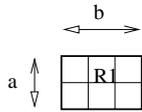


parapente

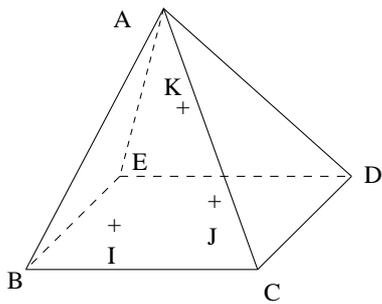
perim.ps



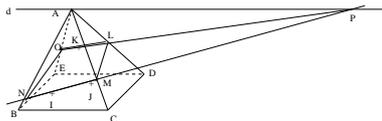
proportions



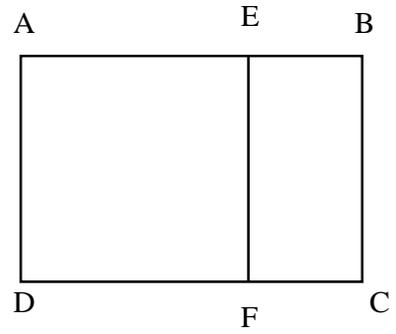
pyramide1



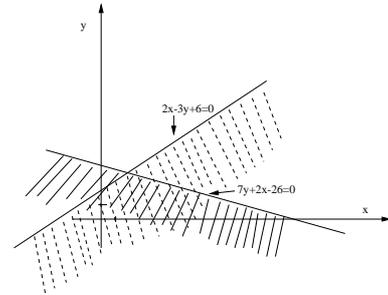
pyramide1c



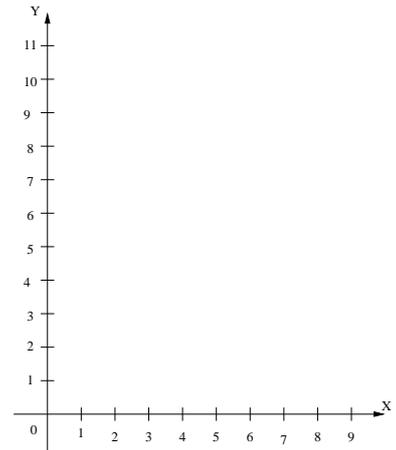
rectangle01



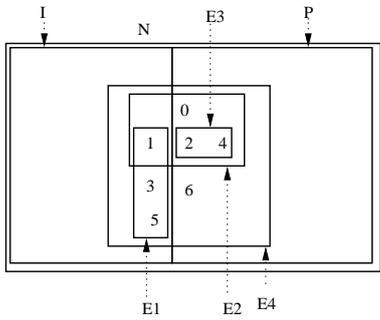
region1



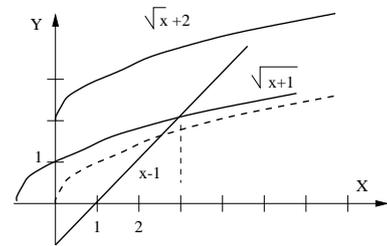
repere



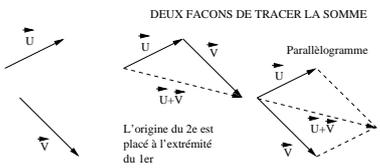
sets1



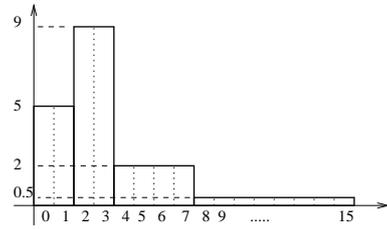
sqrtxc



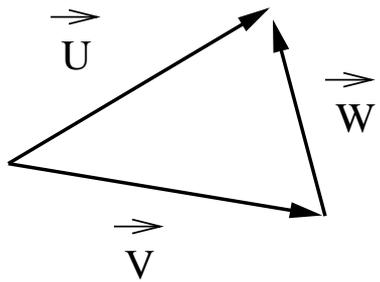
somme



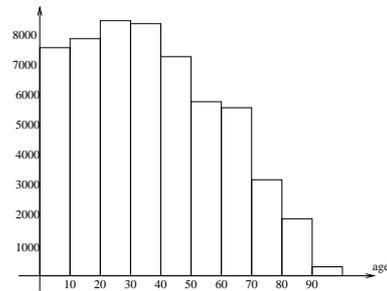
stat1



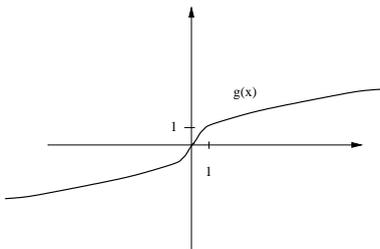
somme2-vecteurs



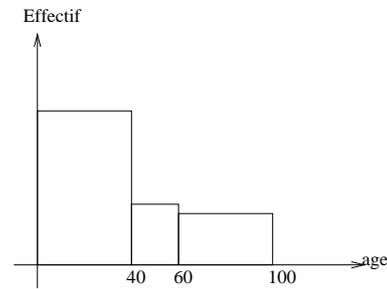
stat2



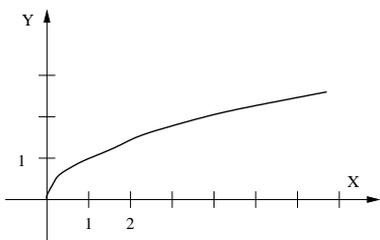
sqrtimpaire



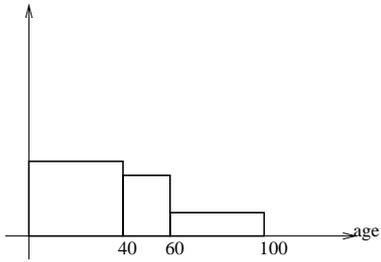
stat3a



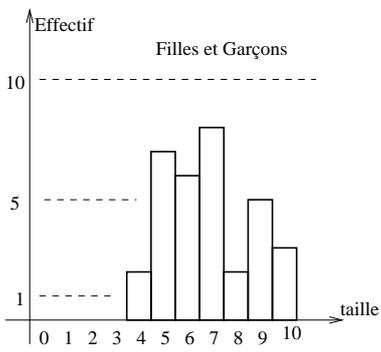
sqrtx



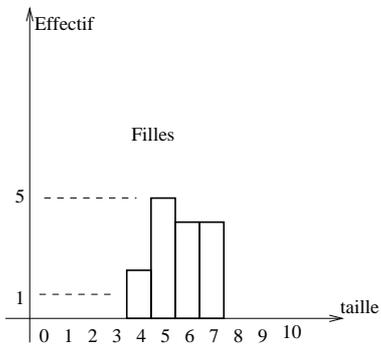
stat3b



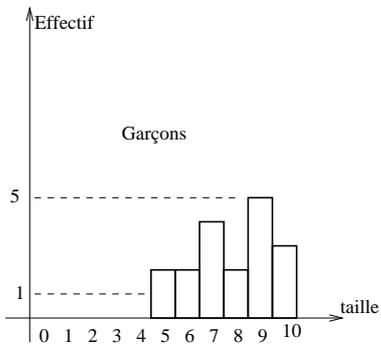
stat4a



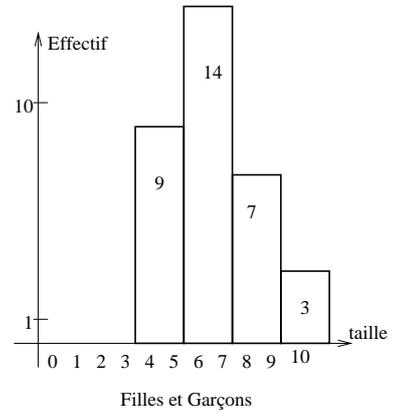
stat4b



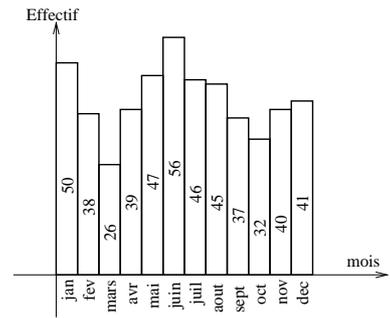
stat4c



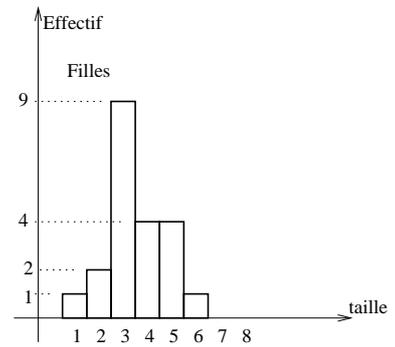
stat4d



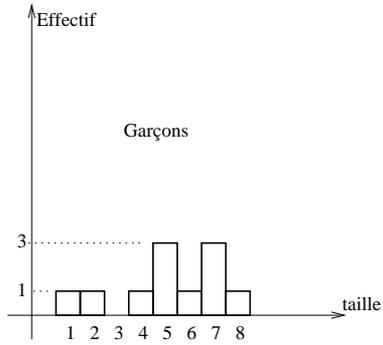
stat5



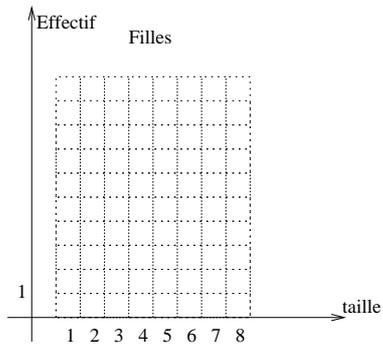
stat6a



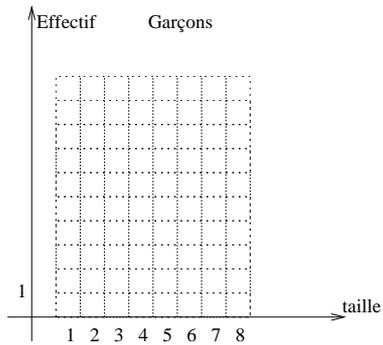
stat6b



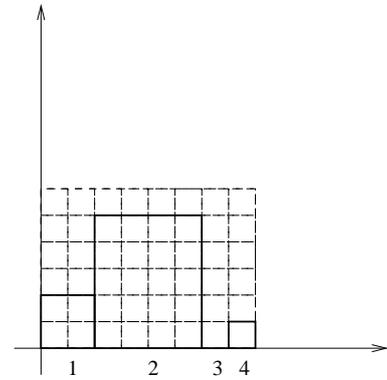
stat6c



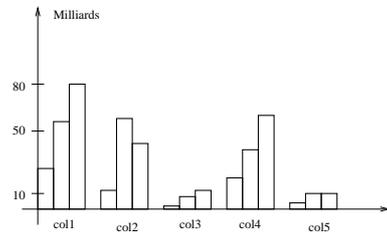
stat6d



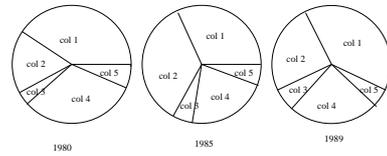
stat7



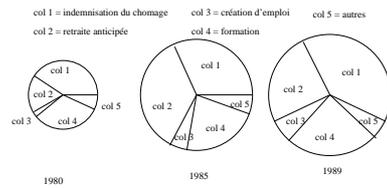
stat8



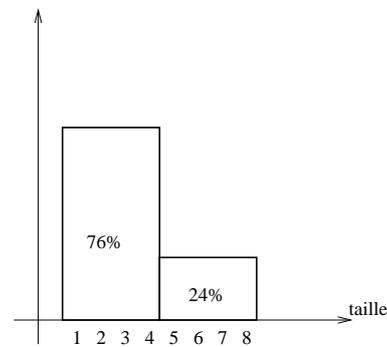
stat9



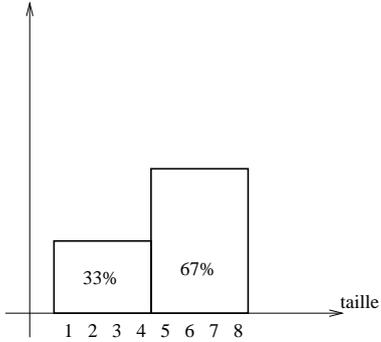
stat10



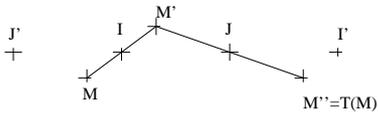
stat11



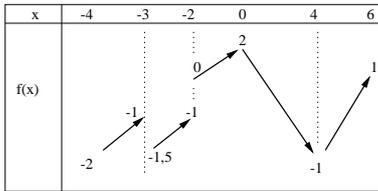
stat12



symetrie01



tabl-variations01



tabl1

x	$-\infty$	$-1/2$	3	∞
$1+2x$	-	0	+	+
$3-x$	+	+	0	-
$(1+2x)(3-x)$	-	0	0	-

tabl2

x	∞	$-1/2$	0	3	∞
$1+2x$	-	0	+	+	+
$3-x$	+	+	+	0	-
x	-	-	+	+	+
$(1+2x)(3-x)/x$	+	-	+	-	-

tabl3

x	$-\infty$	2	4	∞
$x-2$	-	0	+	+
$4-x$	+	+	0	-
$(x-2)(4-x)$	-	0	0	-

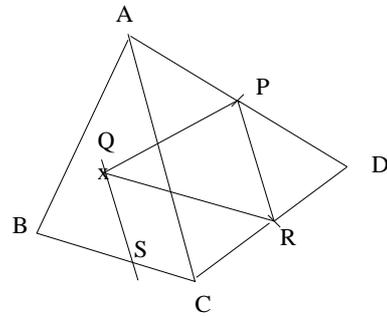
tableau1

x	$-\infty$	-2	0	2	∞
x	-	-	0	+	+
$x-2$	-	-	-	0	+
$x+2$	-	0	+	+	+
$x(x-2)(x+2)$	-	0	+	0	+

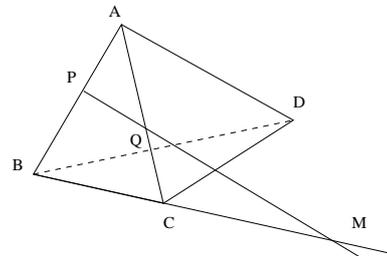
tableau2

x	$-\infty$	-2	0	2	∞
x	-	-	+	+	+
$x-2$	-	-	-	0	+
$x+2$	-	0	+	+	+
$(x-2)(x+2)/x$	-	0	+	-	+

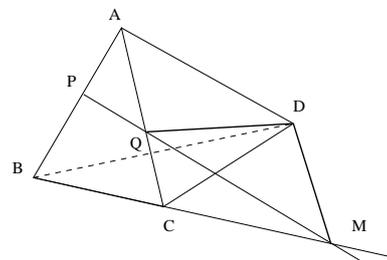
tetraedre1



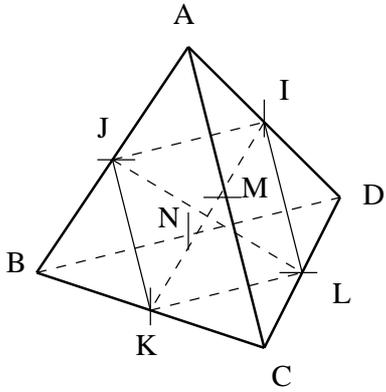
tetraedre2



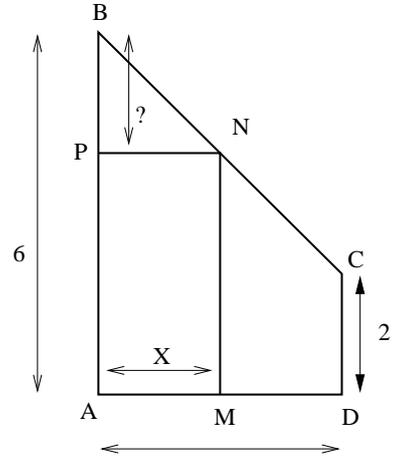
tetraedre2c



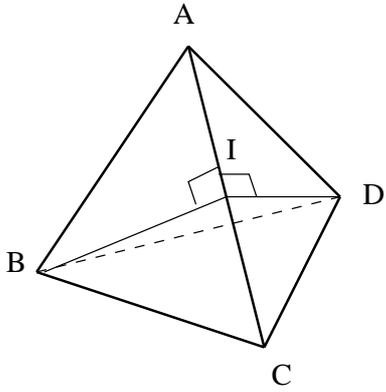
tetraedre3c



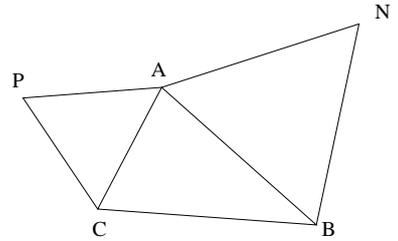
tetraedre4c



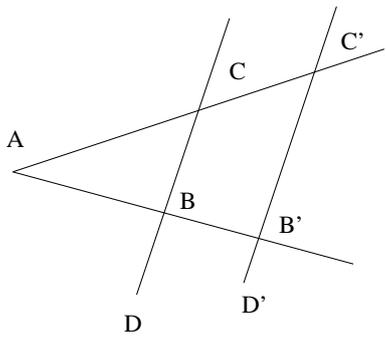
triangle1



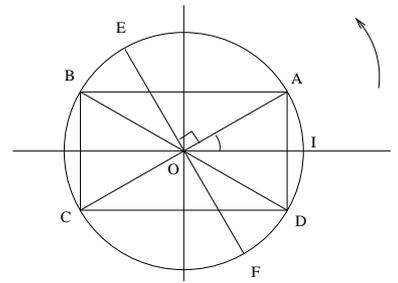
thales01



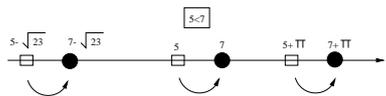
trigo-cercle



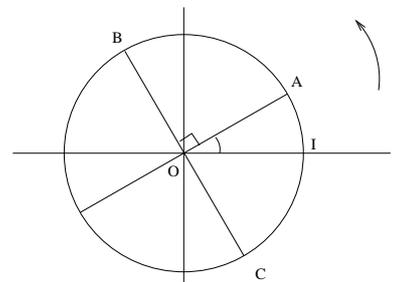
translation



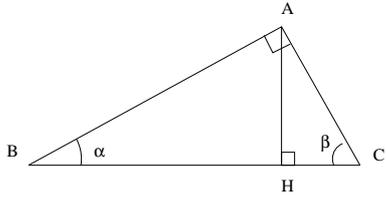
trigo2-cercle



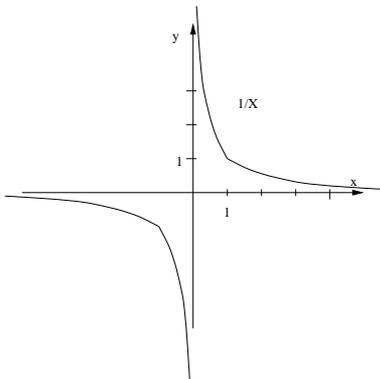
trapeze01



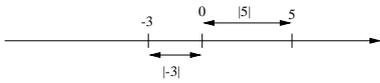
trigo3



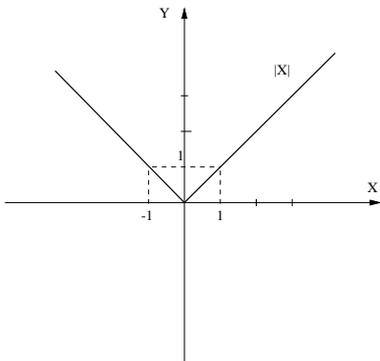
un-sur-x



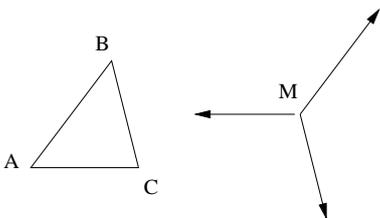
val-abs-exemple



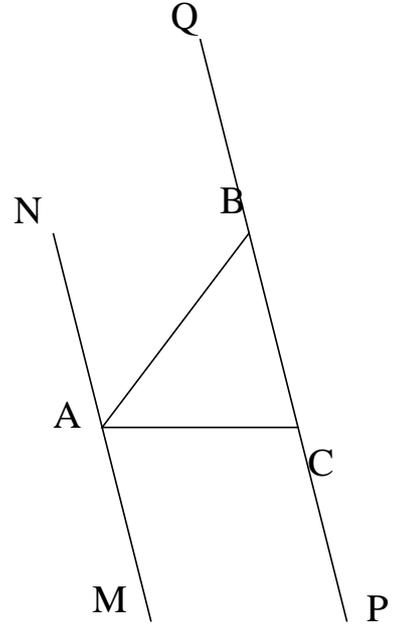
val-abs



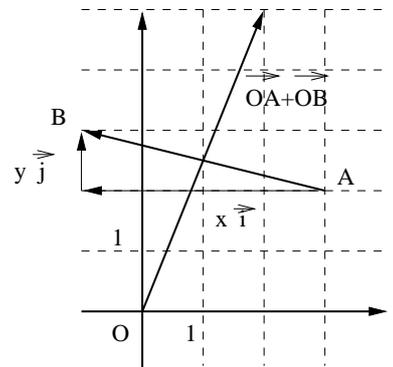
vect-exo1



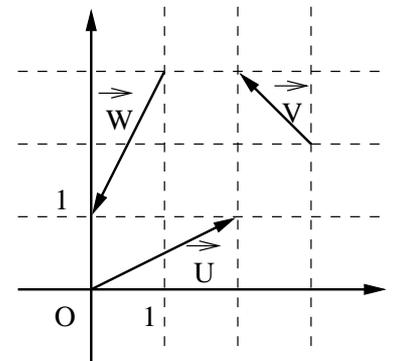
vect-exo2



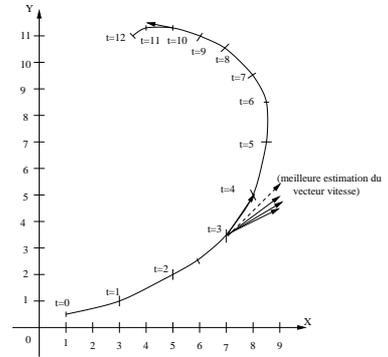
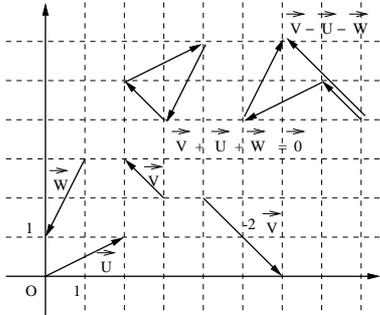
vecteur-add2



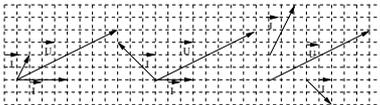
vecteur-addition



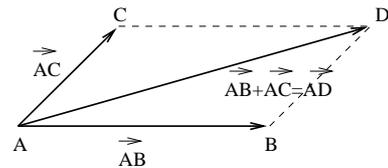
vecteur-add-corr



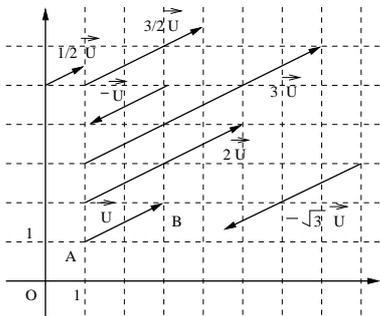
vecteur-coord



vect-somme

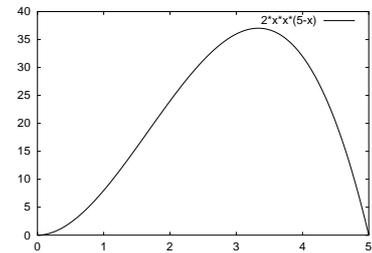
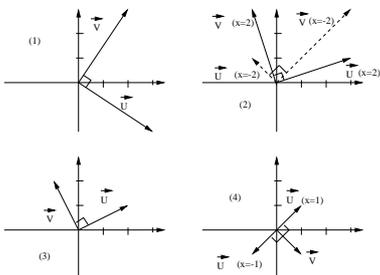


vecteur-mult



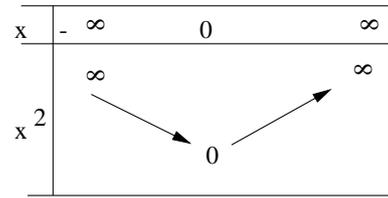
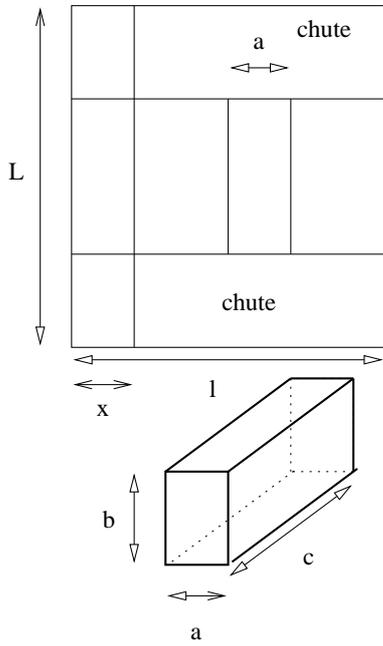
vol.ps

vecteurs-ortho

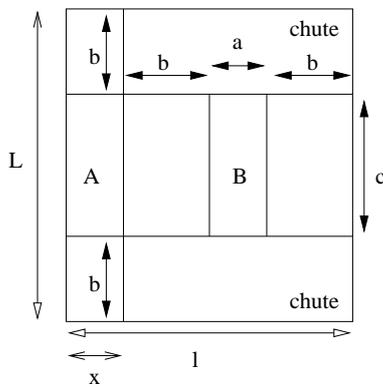


vecteur-vitesse

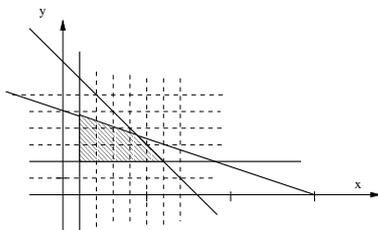
volume01



volume01-c



wagon-sol



x2tableau